Crustal structure beneath NE China imaged by NECESSArray receiver function data

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\textbf{A B S T R A C T}

We analyzed tens of thousands of receiver-function data recorded by 185 broadband seismic stations to study the crustal structure beneath the northeast China. Moho depth and average crustal $V_p/V_s$ ratio were measured at each station using the $H-\kappa$ grid searching technique. For stations located above unconsolidated sediments, we applied the $H-\beta$ method to remove strong shallow reverberations and generate subsurface receiver functions that allow for effective $H-\kappa$ analysis. The measurements show that the Songliao basin has a relatively thin crust ($\sim 31$ km), and the Moho depth increases significantly from southeast ($\sim 27$ km) to northwest ($\sim 35$ km). The northwestward tilting of the Songliao basin may suggest that it was initiated by lithospheric flexure due to the load of the Great Xing'an range in the Jurassic before the large-scale extension in the Cretaceous. Moho depth varies from 26.7 km to 42.3 km across the study area, with the shallowest and deepest Moho being located at the eastern flank of the Songliao basin and the Great Xing'an range, respectively. The Moho depth correlates well with the surface topography in the western part, but not the central and eastern parts of the study area. The residual topography computed based on the Airy's isostasy model indicates that the high topography at the eastern flank of the Songliao basin, the Changbaishan volcanic center, and the southern end of the Great Xing'an range is likely dynamically supported by the upper mantle.

\section{1. Introduction}

The northeast China consists of the northeast China plain (Songliao basin) in its center, the Great Xing'an range to the west, the Changbaishan mountain range and Zhangguangcai range to the east (Fig. 1). The region is bounded by the Sino–Korean craton (also known as the North China craton) in the south at the Solonker suture zone where the paleo-Asian ocean closed at the end of Permian or early Triassic (Chen et al., 2000; Shi et al., 2004). To the north, it is bounded by the Siberian craton at the Mongol–Okhotsk suture (Fig. 1 inset) where the Mongol–Okhotsk Ocean closed progressively from west to east between the middle and late Jurassic (e.g., Meng, 2003; Kravchinsky et al., 2005).

During the later Jurassic and Cretaceous, northeast China experienced large-scale crustal extension and extensive volcanism (Meng et al., 2003), leading to the formation of the Songliao basin and its surrounding volcanic mountains. The cause of the crustal extension and volcanism has been extensively studied and no consensus has been reached. The westward subduction and eastward rollback of the paleo-Pacific plate have been proposed to cause the observed widespread extension and volcanism (Watson et al., 1987; Davis et al., 2004; Ren et al., 2002). On the other hand, several studies (Gao et al., 2004; Wang et al., 2006; Li et al., 2012) suggested that the Cretaceous rifting is likely related to the progressive west to east closure of the Mongol–Okhotsk Ocean. The post-closure collision led to lithospheric thickening of northeast China, and the later collapse of the thickened lithosphere caused convective thinning of the thermal boundary layer.
We found that teleseismic recordings at stations inside the Songliao basin and other basins usually exhibit strong sediment reverberations after the direct P arrival, making it nearly impossible to utilize receiver function techniques (Cassidy, 1992; Sheehan et al., 1995; Zelt and Ellis, 1998). For these stations, we applied the $H-\beta$ analysis developed by Tao et al. (2014), which provides an effective way to remove the shallow reverberations by downward propagating the surface wavefield to the top of the bedrock, leading to better measurements of crustal structure. Our main goal is to present a crustal thickness model of the area as a constraint for ongoing geological and geodynamical studies. An accurate crustal model is also essential to determine the deep lithosphere and mantle structures.

2. Data and analysis

2.1. NECESSArray

We used the waveform data recorded by the NECESSArray, which consists of 127 temporary (blue squares in Fig. 1) and ~82 permanent broadband stations (black triangles in Fig. 1). The 127 temporal stations were deployed under an international collaboration among China, Japan and US in northeast China between September of 2009 and August of 2011. The permanent stations belong to 6 provincial networks (Beijing, Hebei, Liaoning, Inner Mongolia, Jilin, and Helongjiang provinces) of the China Earthquake Administration (CEA) in the study area (Zheng et al., 2009). The array covers an area of 116°–134° east and 41.5°–49.0° north, roughly ~1800 km and ~800 km in the EW and NS direction, respectively (Fig. 1). The average station spacing is ~80 km, which is still too coarse to apply modern array processing techniques, such as common-conversion-point gathering and pre-stack depth migration, to image the Moho. Thus we employed the single station stacking technique to extract the crustal structure around each station.
of the corner frequency of the Gaussian low pass filter. 0.01 and nents. Niu and Li (2011) found a significant portion of the CEA 3-component seismograms into the radial and transverse compo- 
ponents to the principal directions (longitudinal and in-plane transverse) of the covariance matrix computed from the P-wave data. The receiver functions were then computed from the data projected into this coordinate system (hereafter referred to as P- and SV-component) (Vinnik, 1977; Niu and Kawakatsu, 1998; Niu et al., 2005).

We employed the “water-level” deconvolution technique (Clayton and Wiggins, 1976; Ammon, 1991) to generate receiver functions by a division in frequency domain:

\[ RF(\omega) = \frac{V(\omega) \times P^*(\omega)}{\max(|P(\omega)|^2, k \times |P_{max}(\omega)|^2)} e^{-i(\pi/2)}. \]  

(1)

Here \( k \) and \( a \) are two constants that define the “water level” and the corner frequency of the Gaussian low pass filter. \( k \) was set to 0.01 and \( a \) was set to 1.5, which is equivalent to a corner frequency of \( \sim 0.5 \) Hz. \( P(\omega) \) and \( V(\omega) \) are the spectra of the P and SV components. We used a 60 s time window (5 s before and 55 s after the P wave) for \( M \leq 7.0 \) earthquakes and a 100 s time window (5 s before and 95 s after the P wave) for earthquakes with a magnitude greater than 7. Using the similar way of deconvolution, we also generate receiver functions with the radial and vertical components. We first visually inspected all the receiver functions and removed those with low SNR. At each station, we further calculated the covariance matrix of all the receiver functions and discarded those that showed a low cross correlation coefficient (<0.7) with other traces (Chen et al., 2010). The total number of receiver functions used in the final analysis is 35 527. The number of receiver functions selected for each stations varies from 8 to 315, with an average of \( \sim 160 \). Among the 185 stations that have robust measurements, 171 stations have more than 30 good quality receiver functions.

An example of the receiver functions, which are generated with the P- and SV-components, is shown in Fig. 3a–b. There are two positive pulses after the direct P wave at \( \sim 4.4 \) s and 14.8 s, which are expected to be Moho P-to-S conversion phase and the first crustal multiple, 2p1s (Niu and James, 2002). Based on their ray paths, these two phases are expected to have a slightly lower and higher ray parameter (horizontal slowness) than the direct P wave, respectively. In order to determine the relative slowness of these two arrivals and other later phases with respect to the direct P wave, we computed the vespagram of the two sets of receiver functions. To do so, we stacked the receiver functions with linear moveout corrections corresponding to a range of slownesses (e.g., Kawakatsu and Niu, 1994). There are a total of three clear later arrivals shown in the stacked receiver functions. The first later arrival has a slightly negative relative slowness, while the second and third arrivals show positive relative slowness (Fig. 3c–d), indicating that they are the Moho Ps conversion phase and two Moho reverberations, respectively.

2.3. Depth stacking and \( H-\kappa \) analysis

Following Niu et al. (2007), we took two steps to determine the Moho depth and the average \( Vp/Vs \) ratio (\( \kappa \)) of the crust beneath a station. Moho depths are referred from the mean sea level and are computed by subtracting station elevations from the measured crustal thickness. We first used a depth-gathering method to determine an initial depth of the Moho beneath a station. Then we employed a refined \( H-\kappa \) analysis to determine the final estimates of depth and \( Vp/Vs \) that best explain the observed P to S conversion and the reverberation phases. To obtain the initial depth, we first gathered receiver functions recorded at each station and made a time to depth conversion by assuming that P-to-S conversions are the primary sources of energy in the P-wave coda window. For a conversion depth, \( d \), we first computed the relative arrival time of the converted phase, Pds, with respect to the direct arrival by ray tracing the two phases using a modified 1D iasp91 velocity model (Kennett and Engdahl, 1991), which has a lower crust extending to a depth of 65 km. We then summed the receiver function values averaged in a 0.1 s window centered on the arrival time of Pds using both linear and non-linear stacking technique (e.g., Muirhead, 1968; Kawakatsu and Niu, 1994). We varied \( d \) from 0 to 100 km at an increment of 1 km and used the depth with maximum stacking amplitude as the Moho depth. The stacked depth profile at station YANE68 is shown in Fig. 4a, which exhibits a clear P-to-S conversion peak at the depth of 35 km.

The crustal thickness, \( H \), estimated with the above depth gathering method depends on the reference velocity model. There is a strong trade off between \( H \) and the \( Vp/Vs \) ratio or \( Vp \) (Nair et al., 2006). Adding the two crustal multiples (2p1s and 1p2s, Niu and James, 2002) in the stacking can, in principle, resolve the trade off (Zhu and Kanamori, 2000). In most of studies, however, the two multiples are assigned a low weight in the stacking due to the low SNR of the two phases. This can introduce large trade off between

Fig. 2. Distribution of the 788 earthquakes (red stars) used in this study. The blue triangle indicates the center of the seismic array. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)
Fig. 3. (a) An example of the individual SV/P receiver functions recorded at station YP.NE86 located in the Great Xing’an range, plotted as a function of epicentral distance. (b) The receiver functions shown in (a) are stacked in 5° bins with increment of 1°. (c) The linearly stacked receiver functions with the Ps slowness (red solid line) and the 2p1s slowness (blue dotted lines). Vertical dashed lines indicate the Ps, 2p1s and 1p2s phase, respectively. (d) Same as (c) except for the stacking method, which is a 2nd-root stack. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

H and κ. Niu et al. (2007) introduced a coherence index of the three phases, \( c(κ) \), which is computed from the cross correlations between depth traces, to reduce the \( H-κ \) tradeoff:

\[
s(H, κ) = \frac{c(κ)}{N} \sum_{i=1}^{N} \{w_1 r_1(t_i) + w_2 r_2(t_i) - w_3 r_3(t_i)\}.
\]

Here \( N \) is the number of receiver functions at a given station and \( r_i(t) \) represents the amplitude of the \( i \)th receiver function at the predicted arrival times of the primary P-to-S converted phase \( 0p1s(t_1) \), and the two crustal multiples, \( 2p1s(t_2) \) and \( 1p2s(t_3) \). \( w_1, w_2, \) and \( w_3 \) are the weights of the three phases, which are assigned to 0.5, 0.25, and 0.25, respectively. We searched for \( H \) within ±20 km of the initial depth determined from the above depth gathering with a step of 0.1 km. \( κ \) was varied in the range of 1.5 to 2 with an increment of 0.001. \( H \) and \( κ \) were finally determined by picking the location where the summed amplitude, \( s(H, κ) \), reached its maximum. For each station, we used a 1D P-wave velocity model derived from a 3D traveltome tomography study by Sun and Toksoz (2006). The \( H-κ \) stacking result at YP.NE86 is shown in Fig. 4b, which exhibits a well-defined peak at \( H = 36.4 \) km and \( κ = 1.717 \).

2.4. \( H-β \) analysis for basin stations

In general, our \( H-κ \) analysis technique worked well at most of the stations in northeast China. As an example shown in Figs. 3 and 4, the Moho P-to-S conversion and at least one of the two reverberation phases can be clearly observed on the stacked receiver functions, leading to a well-defined peak in the \( H-κ \) diagram. However, the \( H-κ \) analysis failed at a number of stations that were located inside the Songliao, Erlian, and Sanjiang basins. The receiver functions generated at these stations had very strong shallow reverberations after the direct P arrival, resulting in multiple peaks in the \( H-κ \) domain (Fig. 5). As stated before, the strong sediment reverberations have been always the barriers to implementing receiver-function techniques. For these stations we applied the \( H-β \) technique (Tao et al., 2014) that we developed recently to estimate sediment thickness, as well as crustal structure.

Here we briefly review the method proposed by Tao et al. (2014) to estimate sediment and crustal structures beneath a seismic station, which is based on wavefield downward continuation and decomposition. The method parameterizes velocity structure beneath the station with a stack of constant velocity layers overlying a homogeneous half space, and approximates the teleseismic
P-wave and its coda by structural response of an incoming plane P wave. It is based on the principle that the upgoing S wavefield is absent in the half space, and searches for the optimum velocity and thickness of the layers that give the minimum S-wave energy flux from the half space to the layers, which is implemented in an iteratively grid search.

More specifically, we assumed that the crust in the basin consists of two homogeneous layers: an unconsolidated sediment layer and the underlying crystalline crust. We assumed that the P-wave velocity and density are known, which are (2.1 km/s, 1.97 g/cm³) for the sediment, and (6.4 km/s, 2.7 g/cm³) for the crust. The half-space mantle has a seismic structure of 8.0 km/s, 4.5 km/s, and 3.3 g/cm³ for P-, S-wave velocity, and density, respectively. We only searched the thickness and S-wave velocity of the sediment and hard-rock crust to minimize upgoing S wave energy fluxing from the half-space mantle to the crust. An example of the H–β searching result at the YP.NE5 station is plotted in Fig. 6a–b, which shows that the final estimates of the thickness and S-wave velocity of the sediment and underlying crust are (0.59 km, 0.61 km/s) and (31.6 km, 3.67 km/s), respectively.

We further applied the wavefield downward-continuation technique to propagate the surface records to the top of the crystalline crust, and then formed subsurface receiver functions by deconvolving the upgoing P wave from upgoing S waves at the top of the crust (Fig. 6c–d). In principle the wavefield at the top of the crust is not contaminated by sediment multiples. This is demonstrated by comparing the subsurface receiver functions in Fig. 6c–d with those of the regular receiver functions (Fig. 5a–b). While the surface receiver functions are dominated by large-amplitude shallow reverberations that completely mask out the Moho related arrivals (Fig. 5a–b), the Moho P-to-S conversion and the 2p1s multiple can actually be recognized from the subsurface receiver functions in Fig. 6c–d. Also the H–κ stacking of the sub-surface receiver functions yielded a well-defined peak in the H–κ domain (Fig. 6g). The estimated crustal thickness and Vp/Vs ratio based on the H–κ analysis of the subsurface receiver functions are consistent with the H–β results.

3. Results and discussion

3.1. Crustal thickness and Vp/Vs ratio

Among the 209 stations, we were able to obtain 185 measurements of Moho depth and Vp/Vs ratio including 18 H–β measurements (solid squares and triangles in Fig. 1). The other 24 stations either suffered malfunctions or recorded very noisy data (open squares and triangles in Fig. 1). The results are listed in Table S1. The table is organized by grouping stations in the following tectonic/physiographic regions: the Songliao basin (SLB), the Great Xing’an range (GXA), the Erlian basin (ELB), the Hai-basin (HBL), the Zhangguangcai range (ZGC), the Sanjiang basin (SJB), the Ji-amusi Massif (JMS), and northern edge of the Sino–Korea craton (SKC). In Table S1, we also showed 1σ errors, which were calculated based on a bootstrap method (Efron and Tibshirani, 1986). We note that these are formal errors, which do not include uncertainty in the velocity model, and actual errors are likely higher. As shown by previous studies, κ is almost insensitive to the reference Vp model while H depends monotonically on the assumed Vp value. Chen et al. (2010) found that the model-induced uncertainty in Moho depth is expected to be <6–8%.

The measured crustal thickness shows significant variations across the study area, varying from 26.9 km to 43.5 km with an average of 34.0 km. The shallowest Moho is observed at YP.NE59 at the central eastern edge of the Songliao basin, while the thickest crust is located beneath the station YP.NE52 in the central part of the Great Xing’an range (Fig. 1 and Table S1). The observed crustal thickness roughly shows a positive correlation with surface topography (Fig. 7a), and this correlation appears to hold only in the Great Xing’an range. The observed crustal thickness seems to have no correlation with the observed the Vp/Vs ratio (Fig. 7b), which varies between 1.616 and 1.869 with an average of 1.748. In the following sections, we first show the maps of Moho topography and Vp/Vs ratio through interpolation of the 185 observations in order to better exhibit lateral variations of the two parameters. We further divide the study area into western, central and eastern parts and describe the major features of the crust structure observed in these subareas, with a discussion on their tectonic and dynamic implications.

Following Niu et al. (2007), we employed an inversion method to interpolate the 185 measurements and generate 2D relief maps for Moho depth and Vp/Vs ratio, respectively (Fig. 8). More specifically, we divided the study area from 42.0°N to 49.5°N (latitude) and 116°E to 132°E (longitude) into meshed grids of 0.25° × 0.25°. The total 1885 (29 × 65) unknown parameters of Moho depth were inverted from 185 observations. The kernel matrix has a dimension of 185 × 1885 with 185 non-zero elements (= 1) that correspond to the 185 observations. A regularization that minimizes the first derivative of the model (the flattest Moho) was added to regularize the underdetermined inversion. Details of this algorithm were described in Niu et al. (2007). We must note here that the main purpose for generating the 2D maps is to demonstrate lateral variations in Moho depth and Vp/Vs ratio across the study area. The actual resolution is probably not as high as the 0.25° × 0.25° grid spacing. Moreover, our data have no resolution in the corner regions, which are not shown in Fig. 8.

The thickest crust is found in the western part of the study area, i.e., the Great Xing’an range, the Erlian and Hailar basins. This
Fig. 5. (a) The individual receiver functions generated at the station YP.NEA5 located in the northern Songliao basin, plotted as a function of epicentral distance. Note the large reverberations from the base of the sediments. (b) The receiver functions shown in (a) are stacked in 5° bins with increment of 1°. (c) The linearly stacked receiver functions with the Ps slowness (red solid line) and the 2p1s slowness (blue dotted lines). Vertical dashed lines indicate the Ps, 2p1s and 1p2s phase, respectively. (d) The same as (c) except for the stacking method, which is a 2nd-root stack. (e) Results of the $H-\kappa$ analysis obtained from YP.NEA5. Color contours show the summed amplitude as a function of crustal thickness and $V_p/V_s$ ratio. The two white lines indicate location of the amplitude peak. Note that multiple peaks exist in the ($H, \kappa$) domain. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

Fig. 6. The $H-\beta$ search results, sub-surface receiver functions and the $H-\kappa$ stacking of the sub-surface receiver functions of the station YP.NEA5 shown in Fig. 5. Results of the $H-\beta$ search on the thickness and S-wave velocity of the unconsolidated sediment layer and the underlying crystalline crust are shown in (a) and (b), respectively. Color shows the upgoing S-wave energy normalized by its minimum value as a function of layer thickness and average S-wave velocity. (c) The subsurface receiver functions are computed through downward propagating the surface wavefield to the top of the crystalline crust. Note that the strong reverberations shown in Fig. 5a are largely suppressed. (d) The receiver functions shown in (a) are stacked in 5° bins with increment of 1°. (e) The linearly stacked receiver functions with the Ps slowness (red solid line) and the 2p1s slowness (blue dotted lines). Vertical dashed lines indicate the Ps, 2p1s and 1p2s phase, respectively. (f) Results of the $H-\kappa$ analysis obtained from the subsurface receiver functions shown in (c). Color shows the summed amplitude as a function of crustal thickness and $V_p/V_s$ ratio. The two white lines indicate location of the amplitude peak. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)
Fig. 7. Relationship among surface topography, crustal thickness, and \( V_p/V_s \). The correlation coefficients are indicated in the bottom-right of each plot. (a) and (b) show the surface topography and \( V_p/V_s \) ratio as a function of the crustal thickness, respectively, based on all the 185 measurements. Blue and green symbols indicate measurements from stations located in the west part of the study area, including the Great Xing’an range, the Erlian basin and the Hailar basin. Red and black represent measurements from the central and eastern areas. The estimated crustal thickness generally shows a positive correlation with surface topography but no correlation with \( V_p/V_s \) ratio. Similar plots of the western, central and eastern areas are shown in (c, d), (e, f) and (b, d), respectively. Note that the positive correlation between surface topography and crustal thickness is only clearly shown in the western area, and there is no clear correlation between \( V_p/V_s \) ratio and crustal thickness in all the three regions. The green triangles shown in (a) and (c) indicate stations located at the southern end of the Great Xing’an range, which have elevations higher than those predicted by the Airy isostasy model. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

<table>
<thead>
<tr>
<th>Part of the Area</th>
<th>Surface Topography (km)</th>
<th>Crustal Thickness (km)</th>
<th>( V_p/V_s ) Ratio</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>All</strong></td>
<td>0.25 to 1.52</td>
<td>32.6 to 42.3</td>
<td>1.748</td>
</tr>
<tr>
<td><strong>West</strong></td>
<td>0.25 to 1.52</td>
<td>32.6 to 42.3</td>
<td>1.748</td>
</tr>
<tr>
<td><strong>Middle</strong></td>
<td>0.054 to 0.451</td>
<td>26.9 to 35.6</td>
<td>1.748</td>
</tr>
<tr>
<td><strong>East</strong></td>
<td>0.25 to 1.52</td>
<td>28.4 to 39.3</td>
<td>1.748</td>
</tr>
</tbody>
</table>

part of the area has a topography varying from 0.25 to 1.52 km with an average of 0.81 km. The Moho is located between 32.6 and 42.3 km deep below the mean sea level, with an average depth of 36.3 km. There is a clear positive correlation between the crustal thickness and station elevation (Fig. 7c), suggesting that most of the surface topography is supported by a deep crustal root. On the other hand, the \( V_p/V_s \) ratio appears to have no distinct correlation with the observed crustal thickness (Fig. 7d). The regional average of the \( V_p/V_s \) ratio is 1.748, very close to the average of the whole study area.

The Songliao basin in the middle of the study area is underlain by a thin to moderately thick crust, with thickness varying from 26.9 km to 35.6 km and an average of 31.7 km. The shallowest Moho is observed beneath the eastern edge of the basin at the conjunction with the Zhangguangcai range, while the deepest Moho is located in the northwest corner. The northern Songliao basin (with a latitude higher than 45°N) appears to have a slightly thicker crust (\( \sim 33.2 \) km) than its southern neighbor (\( \sim 32.4 \) km) (Fig. 8a). The post-rift sediment is well developed in the northern Songliao basin, which can reach as thick as 4 km, while the post-rift sediment is found to be less than 1 km in the southern area (Wei et al., 2010). This difference may explain the observed crustal thickness between the northern and southern Songliao basin. Surface topography inside the basin varies from 0.054 km in the west to 0.451 km in the east, with an average of \( \sim 0.206 \) km. There is no obvious correlation between the observed crustal thickness and the surface topography (Fig. 7e), suggesting that the surface topography is balanced by something different from the Airy isostasy model. The Songliao basin has a relatively high \( V_p/V_s \) ratio, partly because of the infilling sediments, which usually have very high \( V_p/V_s \) ratio. There is no obvious correlation between the observed crustal thickness and surface topography or \( V_p/V_s \) ratio (Fig. 7g–h).
inversion method described above to interpolate the 185 measurements and generated a map of the residual topography of the study area.

Fig. 9 shows the resulting residual topography map, which reveals a lateral variation between −1 and 1 km. Negative topographic residuals are observed in the most part of the Great Xing’an range, the northwestern part of the Songliao basin and the Jiamusi Massif (Fig. 9). The southern part of the Songliao basin shows a slightly positive to zero residual, indicating it is nearly under isostatic equilibrium. On the other hand, large positive residuals are shown at the southern tip of Great Xing’an range, the eastern flank of Songliao basin and the Changbaishan mountain range. It appears that most of the Cenozoic volcanism occurred in these regions with positive topographic residuals (Fig. 9).

3.2. Residual topography

Using the observed crustal thickness, we further compute the theoretical topography based on the Airy isostasy model:

\[
\begin{align*}
\hat{h} &= \frac{\rho_m - \rho_c}{\rho_m} H - \frac{\rho_m - \rho_c}{\rho_m} H_0 \\
\end{align*}
\]

where \( H \) is the observed crustal thickness, and \( \hat{h} \) is the expected topography. \( \rho_c \) and \( \rho_m \) are crustal and mantle density. If we take \( \rho_c = 2.67 \text{ g cm}^{-3} \), \( \rho_m = 3.3 \text{ g cm}^{-3} \) and the average crustal thickness \( H_0 = 33.6 \text{ km} \), then Eq. (3) becomes \( \hat{h} = 0.191 \ast H - 6.414 \). Since measurement uncertainty in the crustal thickness is much larger than the surface topography, we thus conducted a L2 linear regression using \( \hat{h} \) as the variable. We obtained \( H = 6.64 \ast h + 31.06 \) for the whole area, and \( H = 5.50 \ast h + 32.67 \) for the western region, which can be converted, respectively, to

\[
\begin{align*}
\hat{h} &= 0.150 \ast H - 4.4669 \\
\hat{h} &= 0.182 \ast H - 5.940.
\end{align*}
\]

We used Eq. (4a) to compute the expected topography from the observed crustal thickness at each station. The residual topography at each station is then computed as the difference between the observed and predicted topography. We further employed the same
The average crustal thickness of the Songliao basin is ∼31.7 km, a few kilometers thinner than those observed beneath cratons around the world that experienced little deformations, for example ∼35 km beneath the Kaapvaal and Zimbabwe cratons in Africa (Nguru et al., 2001) and ∼37 km beneath the Guayana shield in South America (Niu et al., 2007). Lithosphere stretching is believed to be the cause of the thin crust beneath the basin (Lin et al., 1997). Our observations also suggest that the overall thinned crust thickens gradually towards northwest, which is difficult to be explained by a uniform stretching.

The residual topography map (Fig. 9) shows that Songliao basin is surrounded by positive residuals in the east, south and southwest sides, suggesting that the surface topography of the Zhangguangcai range, the Changbaishan mountain range, and the southern end of the Great Xing’an range is likely supported dynamically by mantle upwellings, which are also suggested by other seismic studies such as surface wave tomography, P- and S-wave tomography, and seismic anisotropy (Chen et al., 2012). The upwellings can cause the northwestward tilt of the Songliao basin, resulting in an increase in sediment deposition and crustal thickness towards northwest, which agrees with the observed Moho topography beneath the basin (Fig. 8a). If this is the scenario, then the large scale stretching is expected to occur first, followed by the upwelling event. In other words, the tilt is developed in a later stage after the formation of the basin. Liu et al. (2001) observed a sudden migration of volcanism from the middle part of the Songliao basin to the eastern edge at around 30 Ma. This is consistent with our proposed sequential order of the extension and upwelling events.

Foreland basins are usually developed adjacent and parallel to a mountain belt, because the immense mass created by crustal thickening associated with the evolution of the mountain belt causes the lithosphere to bend, by a process known as lithospheric flexure (Watts, 2001). Another possible explanation for the cause of the northwestward tilting of the Songliao basin thus could be related to lithospheric flexure due to the load of the Great Xing’an range in the west and northwest. The basin formed as a foreland basin, probably in the Jurassic before the large-scale extension occurring in the early Cretaceous. This implies that the Songliao basin experienced a low degree of deformation during the crustal shortening stage associated with the closure of the Mongol–Okhotsk Ocean, probably because of its strong cratonic keel. The large-scale crustal stretching occurring in the Cretaceous was likely caused by backarc extension associated with the westward subduction and eastward rollback of the paleo-Pacific plate.

4. Conclusions

We investigated crustal structure beneath the northeast China using waveform data recorded by 185 broadband seismic stations in the region. The receiver function data revealed the following features of the crust beneath the study area: (1) the crust beneath the Erlian and Hailar basins is much thicker (~38 km) than that (~32 km) beneath the Songliao and Sanjiang basins, suggesting they are formed with different mechanism. (2) The southern end of the Great Xing’an range is underlain by a relatively shallow Moho, indicating that the high surface topography in this area is likely supported dynamically by a mantle upwelling, which is also suggested by other seismic data. (3) The Moho beneath the Songliao basin deepens gradually from southeast to northwest. The northern Songliao basin covered by thick post-rift sediment strata has a slightly thicker crust than the southern Songliao basin. The observed crustal $V_p/V_s$ ratio beneath the Songliao basin is generally higher than the surrounding areas, but shows no significant difference between the southern and northern parts. We speculate that the observed lateral variations in crustal structure beneath the Songliao basin was either developed by mantle upwellings after the rifting or inherited from the initial stage of the formation.

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Appendix A. Supplementary material

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References


